

# Parameter Estimation and Decision Making

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# Outline

## 1 Parameter Estimation

# Example

- Problem:
  - Observe whether the sky is cloudy or not cloudy on  $n$  successive days
  - Predict whether the sky will be cloudy on the  $n + 1^{\text{th}}$  day
- Step 1: **Parameter estimation**
  - Model the **unknown** as a random variable with a parameterized distribution with unknown parameter (**Bayesian**) or Model the **unknown** as a fixed but unknown constant (**Frequentist**).
  - Guess the unknown parameter/constant.
- Step 2: **Decision making**
  - Use guess about unknown parameter to find probability of event of interest
  - Decide based on the probability

## Two Major Categories

Suppose you have  $x_1, x_2, \dots, x_R \sim_{(\text{i.i.d.})} \mathcal{N}(\mu, \sigma^2)$   
But you don't know  $\mu$  (you do know  $\sigma^2$ )

- Maximum Likelihood (MLE): For which  $\mu$  is  $x_1, x_2, \dots, x_R$  most likely?
- Maximum a Posterior (MAP): Which  $\mu$  maximizes  $p(\mu|x_1, x_2, \dots, x_R, \sigma^2)$

### Question

Which one do you prefer?

### Question

Despite the intuitiveness of MAP, we'll spend 95% of our time on MLE. Why?

# Frequentist Estimation Problem

- Problem: find “the true value” of a parameter based on data sample
- Estimator: function from **sample space** to **parameter space**
- Estimate: specific **point** in sample space.
- Loss: measure of error w.r.t. true value of parameter

# Properties of Estimators

- (Asymptotic) Consistency
  - Whether true value is recovered for infinite sample size
- Bias
  - Expected deviation of estimate from true value
- Variance
- Mean squared error
  - Bias-variance trade-off

## Properties of Maximum Likelihood Estimator

- **Asymptotically** Unbiased
- Consistent
- Smallest variance among unbiased estimators (aka. asymptotic efficiency)

# Bayesian Parameter Estimation

- Model parameter  $\theta$  as a random variable
- Prior distribution  $P(\theta)$
- Maximum a posteriori probability estimation problem
  - Find posterior distribution  $P(\theta|D)$  of  $\theta$  given observed data  $D$

$$P(\theta|D) = \frac{P(\theta)P(D|\theta)}{\int P(\theta)P(D|\theta)d\theta}$$

- Likelihood  $L(\theta) = P(D|\theta)$

# Three Types of Point Estimation

- Frequentist:
  - **Maximum likelihood estimator**

$$\theta_{ML} = \arg \max_{\theta} L(\theta) = \arg \max_{\theta} P(D|\theta)$$

- Bayesian:
  - **Maximum a posterior estimator**

$$\theta_{MAP} = \arg \max_{\theta} P(\theta|D) = \arg \max_{\theta} P(\theta)P(D|\theta)$$

- **Bayesian estimator**

$$\theta_{Bayes} = E[\theta] = \int \theta P(\theta|D) d\theta$$

## Question

Can you draw a figure to distinguish the three?



# Outline

We will illustrate how to perform these point estimation using examples.

# Example 1: Maximum Likelihood Estimator

- Given a sequence of coin tosses, guess probability of getting head  $H$
- Model  $X \sim_{\text{i.i.d.}} \text{Ber}(p)$
- Likelihood  $L(p) = P(X_1, X_2, \dots; p)$
- Log likelihood

$$\ell(p) \stackrel{\text{def}}{=} \log L(p) = \sum_i P(X_i; p) = n_H \log p + n_T \log(1 - p)$$

where  $n_H$  is #Heads and  $n_T$  is #Tails in  $N$  tosses

- Maximize  $\ell(p)$  by setting  $\frac{\partial \ell(p)}{\partial p} = 0$  and verify maximality.
- Maximum likelihood estimate

$$\hat{p}_{ML} = \arg \max_p \ell(p) = \frac{n_H}{N}$$

# Example 1: MAP Estimator

Model  $p$  as random variable with a prior distribution

$$p \sim \text{Beta}(a, b); \quad f(p) \propto p^{a-1}(1-p)^{b-1} \quad (\text{Conjugate prior})$$

Formulate posterior distribution

$$p(p|D) \propto f(p) \sum_i P(X_i; p) = p^{a+n_H-1}(1-p)^{b+n_T-1}$$

- Because

$$\pi(p|x) \propto \binom{n}{x} p^x (1-p)^{n-x} \cdot \frac{p^{a-1}(1-p)^{b-1}}{B(a, b)}$$

$$\pi(p|x) \propto p^x (1-p)^{n-x} \cdot p^{a-1} (1-p)^{b-1}$$

$$\pi(p|x) \propto p^{x+a-1} (1-p)^{n-x+b-1} \quad (\text{rearrange } p \text{ and } 1-p \text{ terms})$$

Maximum a posteriori estimate

$$\hat{p}_{MAP} = \arg \max_p p(p|D) = \frac{n_H + a - 1}{N + a + b - 2}$$

# Example 1: Bayes Estimator

Model  $p$  as random variable with a prior distribution

$$p \sim \text{Beta}(a, b); \quad f(p) \propto p^{a-1}(1-p)^{b-1} \quad (\text{Conjugate prior})$$

Formulate posterior distribution

$$\begin{aligned} p(p|D) &\propto f(p) \sum_i P(X_i; p) = p^{a+n_H-1}(1-p)^{b+n_T-1} \\ &= \text{Beta}(a + n_H, b + n_T) \end{aligned}$$

Bayes estimate

$$\hat{p}_B = \mathbb{E}[p \mid X_1, \dots, X_n] = \frac{n_H + a}{N + a + b}$$

# Example 1: Bayes Estimator

$$\begin{aligned}
 \hat{p}_B &= E[p|X_1, \dots, X_n] \\
 &= \frac{n_H + a}{N + a + b} \\
 &= \frac{a + b}{N + a + b} \cdot \frac{n_H}{a + b} + \frac{N}{N + a + b} \cdot \frac{n_H}{N} \\
 &= \frac{a + b}{N + a + b} \cdot E[p] + \frac{N}{N + a + b} \cdot \hat{p}_{ML}
 \end{aligned}$$

- Weighted average of prior mean and MLE
- Weight of MLE proportional to number of observations

# Role of priors

- Uniform prior vs. Beta prior
- With uniform prior

$$f(p) \propto 1$$

$$p(p|D) \propto f(p) \sum_i P(X_i; p) = p^{n_H+1}(1-p)^{n_T+1}$$

$$\hat{p}_{MAP} = \arg \max_p p(p|D) = \frac{n_H + 1}{N + 2}$$

## Example 2: MLE for univariate Gaussian

- Suppose you have  $x_1, x_2, \dots, x_R \sim (\text{i.i.d}) N(\mu, \sigma^2)$
- But you don't know  $\mu$  (you do know  $\sigma^2$ )
- MLE: For which  $\mu$  is  $x_1, x_2, \dots, x_R$  most likely?

$$\mu^{mle} = \arg \max_{\mu} p(x_1, x_2, \dots, x_R | \mu, \sigma^2)$$

## Example 2: Algebra Euphoria

$$\begin{aligned}\mu^{mle} &= \arg \max_{\mu} p(x_1, x_2, \dots, x_R | \mu, \sigma^2) \\ &= \arg \max_{\mu} \prod_{i=1}^R p(x_i | \mu, \sigma^2) \quad (\text{by i.i.d})\end{aligned}$$



## Example 2: Algebra Euphoria

$$\begin{aligned}\mu^{mle} &= \arg \max_{\mu} p(x_1, x_2, \dots, x_R | \mu, \sigma^2) \\ &= \arg \max_{\mu} \prod_{i=1}^R p(x_i | \mu, \sigma^2) && \text{(by i.i.d)} \\ &= \arg \max_{\mu} \sum_{i=1}^R \log p(x_i | \mu, \sigma^2) && \text{(monotonicity of log)}\end{aligned}$$

# Example 2: Algebra Euphoria

$$\begin{aligned}
 \mu^{mle} &= \arg \max_{\mu} p(x_1, x_2, \dots, x_R | \mu, \sigma^2) \\
 &= \arg \max_{\mu} \prod_{i=1}^R p(x_i | \mu, \sigma^2) && \text{(by i.i.d)} \\
 &= \arg \max_{\mu} \sum_{i=1}^R \log p(x_i | \mu, \sigma^2) && \text{(monotonicity of log)} \\
 &= \arg \max_{\mu} \frac{1}{\sqrt{2\pi}\sigma} \sum_{i=1}^R -\frac{(x_i - \mu)^2}{2\sigma^2} && \text{(plug in formula for Gaussian)}
 \end{aligned}$$

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 &= \arg \max_{\mu} \sum_{i=1}^R \log p(x_i | \mu, \sigma^2) && \text{(monotonicity of log)} \\
 &= \arg \max_{\mu} \frac{1}{\sqrt{2\pi}\sigma} \sum_{i=1}^R -\frac{(x_i - \mu)^2}{2\sigma^2} && \text{(plug in formula for Gaussian)} \\
 &= \arg \min_{\mu} \sum_{i=1}^R (x_i - \mu)^2 && \text{(after simplification)}
 \end{aligned}$$

# Intermission: A General Scalar MLE strategy

Task: Find MLE  $\theta$  assuming known form for  $P(\text{Data} \mid \theta, \text{stuff})$

- 1 Write  $\ell = \log P(\text{Data} \mid \theta, \text{stuff})$
- 2 Work out  $\frac{\partial \ell}{\partial \theta}$
- 3 Set  $\frac{\partial \ell}{\partial \theta} = 0$  for a maximum, creating an equation in terms of  $\theta$
- 4 Solve it\*
- 5 Check that you've found a maximum rather than a minimum or saddle-point, and be careful if  $\theta$  is constrained

\*This is a perfect example of something that works perfectly in all textbook examples and usually involves surprising pain if you need it for something new.

Example 2: The MLE  $\mu$ 

$$\begin{aligned}\mu^{mle} &= \arg \max_{\mu} p(x_1, x_2, \dots, x_R | \mu, \sigma^2) \\ &= \arg \min_{\mu} \sum_{i=1}^R (x_i - \mu)^2 \\ &= \mu \text{ s.t. } 0 = \frac{\partial \ell}{\partial \mu} = \dots\end{aligned}$$

Example 2: The MLE  $\mu$ 

$$\begin{aligned}\mu^{mle} &= \arg \max_{\mu} p(x_1, x_2, \dots, x_R | \mu, \sigma^2) \\ &= \arg \min_{\mu} \sum_{i=1}^R (x_i - \mu)^2 \\ &= \mu \text{ s.t. } 0 = \frac{\partial \ell}{\partial \mu} = \frac{\partial}{\partial \mu} \sum_{i=1}^R (x_i - \mu)^2 = \sum_{i=1}^R 2(x_i - \mu)\end{aligned}$$

Example 2: The MLE  $\mu$ 

$$\begin{aligned}\mu^{mle} &= \arg \max_{\mu} p(x_1, x_2, \dots, x_R | \mu, \sigma^2) \\ &= \arg \min_{\mu} \sum_{i=1}^R (x_i - \mu)^2 \\ &= \mu \text{ s.t. } 0 = \frac{\partial \ell}{\partial \mu} = \frac{\partial}{\partial \mu} \sum_{i=1}^R (x_i - \mu)^2 = \sum_{i=1}^R 2(x_i - \mu)\end{aligned}$$

Thus,  $\mu = \frac{1}{R} \sum_{i=1}^R x_i$ .

## Example 2: Lawks-a-lawdy!

$$\mu^{mle} = \frac{1}{R} \sum_{i=1}^R x_i$$

- The best estimate of the mean of a distribution is the mean of the sample!
- ① Unsurprising, but with MLE justifications
- ② Naive and MLE estimates of  $\sigma^2$  will be different



## Example 3: MLE for univariate Gaussian

- Suppose you have  $x_1, x_2, \dots, x_R \sim_{(\text{i.i.d})} \mathcal{N}(\mu, \sigma^2)$
- But you don't know  $\mu$  or  $\sigma^2$
- MLE: For which  $\theta = (\mu, \sigma^2)$  is  $x_1, x_2, \dots, x_R$  most likely?

$$\log p(x_1, x_2, \dots, x_R | \mu, \sigma^2) = -R(\log \pi + \frac{1}{2} \log \sigma^2) - \frac{1}{2\sigma^2} \sum_{i=1}^R (x_i - \mu)^2$$

$$\frac{\partial \ell}{\partial \mu} = \frac{1}{\sigma^2} \sum_{i=1}^R (x_i - \mu)$$

$$\frac{\partial \ell}{\partial \sigma^2} = -\frac{R}{2\sigma^2} + \frac{1}{2\sigma^4} \sum_{i=1}^R (x_i - \mu)^2$$

## Example 3: MLE for univariate Gaussian

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$$0 = \frac{1}{\sigma^2} \sum_{i=1}^R (x_i - \mu)$$

$$0 = -\frac{R}{2\sigma^2} + \frac{1}{2\sigma^4} \sum_{i=1}^R (x_i - \mu)^2$$

## Example 3: MLE for univariate Gaussian

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$$0 = \frac{1}{\sigma^2} \sum_{i=1}^R (x_i - \mu) \Rightarrow \mu = \frac{1}{R} \sum_{i=1}^R x_i$$

$$0 = -\frac{R}{2\sigma^2} + \frac{1}{2\sigma^4} \sum_{i=1}^R (x_i - \mu)^2 \Rightarrow \text{what?}$$

## Example 3: MLE for univariate Gaussian

- Suppose you have  $x_1, x_2, \dots, x_R \sim_{(\text{i.i.d})} \mathcal{N}(\mu, \sigma^2)$
- But you don't know  $\mu$  or  $\sigma^2$
- MLE: For which  $\theta = (\mu, \sigma^2)$  is  $x_1, x_2, \dots, x_R$  most likely?

$$\log p(x_1, x_2, \dots, x_R | \mu, \sigma^2) = -R(\log \pi + \frac{1}{2} \log \sigma^2) - \frac{1}{2\sigma^2} \sum_{i=1}^R (x_i - \mu)^2$$

$$\mu^{mle} = \frac{1}{R} \sum_{i=1}^R x_i$$

$$\sigma_{mle}^2 = \frac{1}{R} \sum_{i=1}^R (x_i - \mu^{mle})^2$$

# Unbiased Estimators

- An estimator of a parameter is **unbiased** if the expected value of the estimate is the **same** as the true value of the parameters.
- If  $x_1, x_2, \dots, x_R \sim_{(\text{i.i.d})} \mathcal{N}(\mu, \sigma^2)$  then

$$\mathbf{E}[\mu^{mle}] = \mathbf{E}\left[\frac{1}{R} \sum_{i=1}^R x_i\right] = \mu$$

- Hence,  $\mu^{mle}$  is unbiased

# Biased Estimators

- An estimator of a parameter is **biased** if the expected value of the estimate is **different from** the true value of the parameters.
- If  $x_1, x_2, \dots, x_R \sim_{(i.i.d)} \mathcal{N}(\mu, \sigma^2)$  then

$$\mathbf{E} \left[ \sigma_{mle}^2 \right] = \mathbf{E} \left[ \left[ \frac{1}{R} \sum_{i=1}^R (x_i - \mu^{mle})^2 \right] \right] = \mathbf{E} \left[ \left[ \frac{1}{R} \sum_{i=1}^R \left( x_i - \frac{1}{R} \sum_{j=1}^R x_j \right)^2 \right] \right] \neq \sigma^2$$

- Hence,  $\sigma_{mle}^2$  is biased

## MLE Variance Bias

- If  $x_1, x_2, \dots, x_R \sim_{(i.i.d)} \mathcal{N}(\mu, \sigma^2)$  then

$$\mathbf{E} \left[ \sigma_{mle}^2 \right] = \mathbf{E} \left[ \frac{1}{R} \sum_{i=1}^R \left( x_i - \frac{1}{R} \sum_{j=1}^R x_j \right)^2 \right] = \left( 1 - \frac{1}{R} \right) \sigma^2 \neq \sigma^2$$

- Intuition check: consider the case of  $R = 1$

## Question

Why should our guts expect that  $\sigma_{mle}^2$  would be an underestimate of true  $\sigma^2$ ?

## Question

How could you prove

$$\mathbf{E} \left[ \frac{1}{R} \sum_{i=1}^R \left( x_i - \frac{1}{R} \sum_{j=1}^R x_j \right)^2 \right] = \left( 1 - \frac{1}{R} \right) \sigma^2?$$

# Unbiased estimate of Variance

- If  $x_1, x_2, \dots, x_R \sim (\text{i.i.d}) \mathcal{N}(\mu, \sigma^2)$  then

$$\mathbf{E} \left[ \sigma_{mle}^2 \right] = \mathbf{E} \left[ \frac{1}{R} \left( \sum_{i=1}^R x_i - \frac{1}{R} \sum_{j=1}^R x_j \right)^2 \right] = \left( 1 - \frac{1}{R} \right) \sigma^2 \neq \sigma^2$$

So define  $\sigma_{\text{unbiased}}^2 = \frac{\sigma_{mle}^2}{\left(1 - \frac{1}{R}\right)}$

And  $\mathbf{E} \left[ \sigma_{\text{unbiased}}^2 \right] = \sigma^2$

$$\sigma_{\text{unbiased}}^2 = \frac{1}{R-1} \sum_{i=1}^R (x_i - \mu^{mle})^2$$



# Unbiasedness discussion

## Question

Which one is better?

$$\sigma_{mle}^2 = \frac{1}{R} \sum_{i=1}^R (x_i - \mu^{mle})^2$$

$$\sigma_{unbiased}^2 = \frac{1}{R-1} \sum_{i=1}^R (x_i - \mu^{mle})^2$$

# Unbiasedness discussion

## Question

Which one is better?

$$\sigma_{mle}^2 = \frac{1}{R} \sum_{i=1}^R (x_i - \mu^{mle})^2$$

$$\sigma_{unbiased}^2 = \frac{1}{R-1} \sum_{i=1}^R (x_i - \mu^{mle})^2$$

Answer:

- It depends on the task
- And doesn't make much difference once  $R \rightarrow$  large

# Don't get too excited about being unbiased

- Assume  $x_1, x_2, \dots, x_R \sim_{\text{(i.i.d)}} \mathcal{N}(\mu, \sigma^2)$
- Suppose we had these estimators for the mean

$$\mu^{\text{suboptimal}} = \frac{1}{R + 7\sqrt{R}} \sum_{i=1}^R x_i$$

$$\mu^{\text{crap}} = x_1$$

## Questions

- Are either of these unbiased?
- Will either of them asymptote to the correct value as  $R$  gets large?
- Which is more useful?

# Decision Theory

- Choose a specific point estimate under uncertainty
- Loss functions measure extent of error
- Choice of estimate depends on loss function

# Loss Functions

- 0-1 loss

$$L(y, a) = I(y \neq a) = \begin{cases} 0 & \text{if } a = y \\ 1 & \text{if } a \neq y \end{cases}$$

- Minimized by MAP estimate (posterior mode)

- $l_2$  loss

$$L(y, a) = (y - a)^2$$

- Expected loss:  $E[(y - a)^2 | x]$  (Min mean squared error)
- Minimized by Bayes estimate (posterior mean)

- $l_1$  loss

$$L(y, a) = |y - a|$$

- Minimized by posterior median

# Loss Functions

- Cross-entropy loss

- Binary classification:  $y$  is the prob of positive class

$$L(y, a) = y \log(a) + (1 - y) \log(1 - a)$$

- Multi-class classification:  $y(a)$  is the prob distribution of all  $K$  classes, and  $k$  is the true class

$$L(y, a) = \log(a_k), k \text{ is the true class}$$

- Equivalent to KL divergence

$$H(y, a) = H(y) + D_{KL}(y||a)$$

# Predictive distribution

- Find the probability of the outcome of the  $n + 1^{\text{th}}$  experiment given outcomes of previous  $n$  experiments

$$P(A_{n+1}|A_1, \dots, A_n)$$

- Frequentist
  - Construct point estimate of parameter  $\hat{\theta}$  from  $n$  outcomes

$$P(A_{n+1}|A_1, \dots, A_n) \cong P(A_{n+1}; \hat{\theta})$$

- Bayesian
  - Consider the entire posterior distribution of  $\theta$

$$P(A_{n+1}|A_1, \dots, A_n) = \int P(A|\theta)P(\theta|A_1, \dots, A_n)d\theta$$

# Summary

- Parameter estimation problem
- Frequentist vs Bayesian
- MLE, MAP and Bayes estimators for Bernoulli trials
- Optimal estimators for different loss functions
- Prediction using estimated parameters